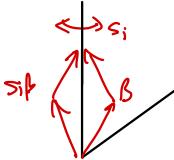


Symmetric Macdonald polynomials

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March 27, 2025



0 Recall

$$T_i = ts_i + \frac{t-1}{e^{\alpha_i} - 1} (s_i - id) \quad \text{Demazure--Lusztig operators for } i \in I$$

extended to $i=0$, so and do

$$Q_{q,t}[\lambda] = \bigoplus_{\lambda \in \Lambda} Q(q,t) e^\lambda \quad \text{factory way of thinking}$$

$\gamma^\beta, \beta \in Q^\vee$ = coroot lattice

Non-sym. Macdonald poly E_λ for $\lambda \in \Lambda$

$$\textcircled{1} \quad Y^\beta(E_\lambda) = q^{-\langle \beta, \lambda \rangle} t^{-\langle \beta, \rho_\lambda \rangle} E_\lambda$$

$$\textcircled{2} \quad E_\lambda = e^\lambda + (\text{other}) \quad \text{Q_{q,t}-linearly}$$

$$\text{"factory way"} \quad Q_{q,t}[Q^\vee] = \bigoplus_{\beta \in Q^\vee} Q_{q,t} Y^\beta \curvearrowright Q_{q,t}[\lambda]$$

$$Q_{q,t}[\lambda] \cong \bigoplus_{\lambda \in \Lambda} Q_{q,t} \cdot E_\lambda \quad \text{as } Q_{q,t}[Q^\vee]-\text{module}$$

Questions For two matrices H and E with relation $HE = E(H+2)$ show that they are simultaneously triangulated intertwine

$$\begin{aligned} \text{If } Hv = \lambda v, \text{ then } H(Ev) = (\lambda+2)Hv. \text{ Then pick} \\ \text{If } Hv = \lambda v, \text{ then that } \lambda+2 \text{ is not an} \\ H(Ev) = E(H+2)v \\ = E(\lambda+2)v = (\lambda+2)Ev. \end{aligned}$$

$$W_\lambda = \{v \in \mathbb{C}^n : Hv = \lambda v\}$$

$$W_\lambda \xrightarrow{E} W_{\lambda+2}$$

Pick any eigenvalue λ of H
st. $\lambda+2$ is not an eigen...



Learning seminar
Macdonald



link

notes

1 Intertwine operators

1.1 Bernstein relations

$$H_i = t^{1/2} T_i$$

Denote $X^\lambda : f \mapsto e^\lambda f$. Then we have

$$H_i Y^\beta - Y^{s_i \beta} H_i = (t^{1/2} - t^{-1/2}) \frac{Y^{s_i \beta} - Y^\beta}{Y^{-\alpha_i^\vee} - 1},$$

$$H_i X^\lambda - X^{s_i \lambda} H_i = (t^{1/2} - t^{-1/2}) \frac{X^{s_i \lambda} - X^\lambda}{X^{\alpha_i^\vee} - 1}.$$

● Standard proof. $Y^\beta = H_{t\beta}$ when $i=0$
Demazure-Lusztig operators
for $i \in I$
 β dom. names
 β dom $\Rightarrow s_i \beta + \beta$ dom (since $s_i \beta$ is NOT dom)
 $Y^{s_i \beta} = Y^{s_i \beta + \beta} / Y^\beta = H_{ts_i \beta + \beta} H_{t\beta}^{-1}$

$$\begin{aligned} \textcircled{1} \quad T_i &= ts_i + \frac{t-1}{e^{\alpha_i} - 1} (s_i - id) \quad X^\lambda = e^\lambda \\ T_i X^\lambda &= \left(ts_i + \frac{t-1}{e^{\alpha_i} - 1} (s_i - id) \right) e^\lambda \\ &= t e^{s_i \lambda} s_i + \frac{t-1}{e^{\alpha_i} - 1} (e^{s_i \lambda} s_i - e^\lambda id) \\ &= \dots \end{aligned}$$

$$\begin{array}{ccc} \text{duality} & \tilde{H}_w & \text{double affine Hecke algebra DAHA} \\ \text{affine Hecke algebra} & \overset{\sim}{\uparrow} & \text{affine Hecke algebra} \\ \text{Q}_{q,t}[Q^\vee] & \overset{\sim}{\leftrightarrow} & H_w \text{ finite Hecke algebra} \\ \text{Q}_{q,t}[\lambda] & \overset{\sim}{\leftrightarrow} & \end{array}$$

1.2 Intertwine operators

For $i \in I$,

$$\tau_i = T_i + \frac{t-1}{Y^{-\alpha_i^\vee} - 1}.$$

Note: $Y^\beta \curvearrowright Q_{q,t}[\lambda]$ does not have eigenvalue 1.

$$T_i Y^\lambda = Y^{s_i \lambda} T_i \quad (\text{intertwine})$$

$$\underbrace{T_i T_j \dots}_{m_{ij}} = \underbrace{\tau_j \tau_i \dots}_{m_{ij}} \quad (\text{braid relation})$$

Rank.

$$X^\lambda : \text{functions} \quad \times^\lambda : \text{operators}$$

$$T_w : \text{operators} \longleftrightarrow T_w : \text{operators}$$

$$Y^\beta : \text{operators} \quad Y^\beta : \text{functions}$$

(DL op in "Y")

$$T_i = T_i + \frac{t-1}{Y^{-\alpha_i^\vee} - 1} = \frac{+Y^{-\alpha_i^\vee} - 1}{Y^{-\alpha_i^\vee} - 1} s_i$$

$\{f(s_i) s_i\}$ satisfies braid relation
for any f .

$$\tau_i = \bar{\tau}_i + \frac{t-1}{q^{(\lambda, \alpha_i^\vee)} - 1}$$

Theorem If $s_i \lambda > \lambda$ for some $i \in I$, i.e. $\langle \lambda, \alpha_i^\vee \rangle > 0$, then

$$E_{s_i \lambda} = \tau_i E_\lambda = \left(\bar{\tau}_i + \frac{t-1}{q^{(\lambda, \alpha_i^\vee)} t^{(\rho_\lambda, \alpha_i^\vee)} - 1} \right) E_\lambda.$$

- ① eigenvalue of y^β at E_λ $\begin{matrix} q^{-\langle \beta, \lambda \rangle} \\ q^t \end{matrix}$ ($s_i \lambda > \lambda$)
 $=$ eigenvalue of $y^{s_i \beta}$ at $E_{s_i \lambda}$ $\begin{matrix} q^{-\langle s_i \beta, s_i \lambda \rangle} \\ q^t \end{matrix}$ $\begin{matrix} -\langle \beta, \lambda \rangle \\ -\langle s_i \beta, s_i \lambda \rangle \end{matrix}$
- ② $y^{s_i \beta} E_{s_i \lambda} = Y^{s_i \beta} \tau_i E_\lambda = \tau_i Y^{s_i \beta} E_\lambda$
 $= (\dots) \tau_i E_\lambda = (\dots) E_{s_i \lambda}.$
 $\Rightarrow \tau_i E_\lambda \in Q_{q,t} E_{s_i \lambda}$
- ③ look at the coefficient of $e^{s_i \lambda}$,
 $\tau_i E_\lambda = E_{s_i \lambda}. \quad \square$

Remarks:

There is a version for $i=0$;
while in type A

- ① If we know E_λ for λ dominant
then we know E_λ for all λ .
- a) The above formula has a version for $i=0$.
b) For type A, you can use automorphism of
root systems. $(3, 4, 2, 0) \rightarrow (1, 3, 4, 2)$

Example GL_2

$$E_{(1,0)} = x_1 \quad T_i(x_1) = x_2$$

$$\begin{aligned} E_{(0,1)} &= (\bar{\tau}_i + \frac{t-1}{q^t - 1}) E_{(1,0)} \\ &= x_2 + \frac{t-1}{q^t - 1} x_1 \end{aligned}$$

- ② $q=0$, the above formula reduces to
 $E_{s_i \lambda} (q=0) = T_i E_\lambda (q=0)$

Key polynomials $K_\lambda = E_\lambda (q=\infty, t=\infty)$

$$K_{s_i \lambda} = \bar{\tau}_i K_\lambda \quad \begin{matrix} \text{proof} \\ \text{① recursion ✓} \\ \text{② initial ?} \end{matrix}$$

- ? $E_\lambda (q=\infty, t=\infty) \neq x^\lambda \quad \lambda \text{ dominant}$
(this can be seen from "Chevalley inner product")

2 a Symmetric Macdonald

is NOT a non-sym Macdonald poly.

$$E_\lambda \in Q_{q,t}[\Lambda] \quad \begin{matrix} \text{Y}^\beta \text{ does not act on } Q_{q,t}[P]^W \\ \text{with } f \text{ symmetric does.} \end{matrix}$$

$Q_{q,t}[\Lambda]^W \not\cong Y^\beta$ sketch of the proof.
 $f(Y) \not\in \text{sym}$.

Lemma $Q_{q,t}[\Lambda^\vee] \cong Q_{q,t}[\Lambda]$ restricts to

$$Q_{q,t}[\Lambda^\vee]^W \cong Q_{q,t}[\Lambda]^W$$

Sketch $C_{w_0} = \sum_{w \in W} T_w$.

$$Q_{q,t}[\Lambda]^W = \text{image of } C_{w_0} \quad \begin{matrix} (\text{Conf sym}) \\ (\text{f sym} \Rightarrow C_{w_0} f = (\dots) f) \end{matrix}$$

$Q_{q,t}[\Lambda^\vee]^W$ commutes with C_{w_0} .
 $(f(Y) C_{w_0} = C_{w_0} f(Y) \text{ if } f \text{ sym})$

$$\stackrel{\text{ex.}}{\Rightarrow} Q_{q,t}[\Lambda^\vee]^W \cong Q_{q,t}[\Lambda]^W \quad \square$$

Symmetric Macdonald poly $P_\lambda \in Q_{q,t}[\Lambda]^W$ definition
for λ dominant, is the unique poly sat.

$$\begin{aligned} \text{① } f(Y) P_\lambda &= f(q^{-\lambda} t^{-\rho}) P^\lambda \\ \text{② } P_\lambda &= m_\lambda + (\text{other}) \end{aligned} \quad f \in Q_{q,t}[\Lambda^\vee]^W$$

$$\begin{aligned} f(q^{-\lambda} t^{-\rho}) &= f(Y) \mid Y^\beta \mapsto q^{-\langle \lambda, \beta \rangle} t^{-\langle \rho, \beta \rangle} \\ m_\lambda &= \sum_{\mu \in W\lambda} e^\mu = \text{orbit sum.} \\ &= \text{monomial basis.} \end{aligned}$$

Lemma For a dominant λ ,

$$P_\lambda \in \text{span}(E_\mu : \mu \in W\lambda).$$

$$\text{RHS} = \{ g \in Q_{q,t}[\Lambda] : \begin{matrix} \forall f \in Q_{q,t}[\Lambda^\vee]^W \\ f(Y)g = f(q^{-\lambda} t^{-\rho})g \end{matrix} \}$$

$$\text{span}(P_\lambda) = \{ g \in Q_{q,t}[\Lambda] : \begin{matrix} \forall f \in Q_{q,t}[\Lambda^\vee]^W \\ f(Y)g = f(q^{-\lambda} t^{-\rho})g \end{matrix} \}$$

$$Q_{q,t}[\Lambda^\vee] \cong Q_{q,t}[\Lambda] = \bigoplus_{\lambda \in \Lambda} Q_{q,t} E_\lambda$$

$$Q_{q,t}[\Lambda^\vee]^W \cong Q_{q,t}[\Lambda] = \bigoplus_{\lambda \text{ dom}} \left(\bigoplus_{\mu \in W\lambda} Q_{q,t} E_\mu \right)$$

$$Q_{q,t}[\Lambda]^W = \bigoplus_{\lambda \text{ dom}} Q_{q,t} P_\mu.$$

Example GL_2

$$E_{(1,0)} = x_1$$

$$E_{(0,1)} = \frac{-t+1}{-qt+1} x_1 + x_2$$

\Downarrow

$$P_{(1,0)} = x_1 + x_2$$

$$E_{(2,0)} = x_1^2 + \left(\frac{-q+t+q}{-qt+1}\right) x_1 x_2$$

$$E_{(0,2)} = \left(\frac{-t+1}{-qt+1}\right) x_1^2 + \left(\frac{-qt+q-t+1}{-q^2t+1}\right) x_1 x_2 + x_2^2$$

\Downarrow

$$P_{(2,0)} = \left(1 - \left(\frac{-t+1}{-qt+1}\right)\right) E_{(2,0)} + E_{(0,2)}$$

$$= x_1^2 + \left(\frac{-q+t+q-t+1}{-qt+1}\right) x_1 x_2 + x_2^2.$$

When λ is dominant

$$P_\lambda = \frac{1}{w_\lambda(t)} \text{Symm}(E_\lambda)$$

left as an exercise.

3 Type A (Sketch)

Theorem P_λ is a symmetric function.

Type A, S_n , \tilde{S}_n , H_n , \tilde{H}_n , P_λ operators Y_1, \dots, Y_n ;
 $Y_1, \dots, Y_n \in \tilde{H}_n$ to stabilize $\sum Y_i \in \mathbb{Q}_{\geq 0}[t]$ w.r.t. t
 Macdonald operators $\tilde{Y}_1, \dots, \tilde{Y}_n \in \tilde{H}_n$
 ① already has distinct eigenvalues on $P_\lambda(x_1, \dots, x_n)$
 ② can be computed explicitly known as "Macdonald operator"

$$\sum_{i=1}^n \left(\prod_{j \neq i} \frac{t^{1/2}x_i - t^{-1/2}x_j}{x_i - x_j} \right) d_i^{-1} \quad d_i f(\dots, x_i, \dots) = f(\dots, q x_i, \dots)$$

To take $n \rightarrow \infty$ limit, we need a modification

$$\frac{1}{q^{-1}-1} \left(t^{\frac{n-1}{2}} (Y_1 + \dots + Y_n) - (t^1 + \dots + t^n) \right)$$

Its eigenvalue at P_μ

$$\sum_{(i,j) \in \mu} \frac{q^{-j-1}}{q} t^{i-1}$$

$$(\bar{q} = q^{-1})$$

$$\Rightarrow P_\mu \in \Lambda.$$

e.g.

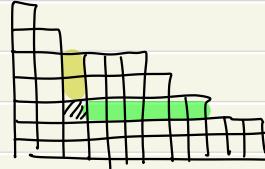


$$\sum \left\{ t, \frac{1}{q}, \frac{1}{q^2}, \frac{1}{q^3} \right\}$$

3.1 Other Macdonald functions

$$J_\lambda = P_\lambda \cdot \prod_{\square \in \lambda} (1 - q^{\alpha(\square)} t^{\ell(\square)+1})$$

transformed
"integral form"
now 1-form metric



$$\alpha(\square) = 6$$

$$\ell(\square) = 2$$

$$H_\lambda = J_\lambda \left[\frac{Z}{1-t} \right] = J_\lambda \begin{pmatrix} x_1, t x_1, t^2 x_1, \dots \\ x_2, t x_2, t^2 x_2, \dots \\ \vdots & \vdots & \ddots \end{pmatrix}$$

$$"Z" = x_1 + x_2 + \dots \text{ all variables} \quad "transformed"$$

$$\frac{1}{1-t} = 1 + t + t^2 + t^3 + \dots$$

$$P_k = x_1^k + x_2^k + x_3^k + \dots$$

$$P_k \left[\frac{Z}{1-t} \right] = x_1^k + (t x_1)^k + (t^2 x_1)^k + \dots$$

$$+ x_2^k + (t x_2)^k + (t^2 x_2)^k + \dots$$

$$f \mapsto f \left[\frac{Z}{1-t} \right] = P_k + t^k P_k + t^{2k} P_k + \dots$$

invertible

$$= \frac{1}{1-t^k} P_k$$

$$\tilde{H}_\lambda = t^{n(\lambda)} H_\lambda |_{t \leftrightarrow t^{-1}} \circ \circ \quad \text{balance } q \text{ and } t$$

Example  $\alpha(\square) = 0, \alpha(\square) = 0$
 $\ell(\square) = 1, \ell(\square) = 0$ $n(\lambda) = 1$

$$P_{(1,1)} = x_1 x_2 + \dots = e_2 = m_{(1,1)}.$$

$$J_{(1,1)} = (1-t)(1-t^2) P_{(1,1)}$$

$$= (t-1)(t^2-1) \frac{P_1 - P_2}{2}$$

$$H_{(1,1)} = (t-1)(t^2-1) \left(\frac{\left(\frac{1}{1-t}\right)^2 P_1 - \frac{1}{1-t^2} P_2}{2} \right)$$

$$= \frac{t+1}{2} P_1 + \frac{t-1}{2} P_2 = (t+1) m_{(1,1)} + t m_{(2)}$$

$$\tilde{H}_{(1,1)} = t((t^2+1)m_{(1,1)} + t^{-1}m_{(2)})$$

$$= (t+1) m_{(1,1)} + m_{(2)}.$$

$$= t S_{(1,1)} + S_{(2)}.$$

$$P_{(2,0)} = m_{(1,1)} + \frac{(q+1)(t-1)}{q t - 1} m_{(2)}.$$

$$J_{(2,0)} = (-)$$

$$H_{(2,0)} = (q+1) m_{(1,1)} + m_{(2)}$$

$$\tilde{H}_{(2,0)} = (q+1) m_{(1,1)} + m_{(2)}$$

$$= q S_{(1,1)} + S_{(2)}.$$

$$\text{In general: } \tilde{H}_\lambda |_{q \leftrightarrow t} = \tilde{H}_{\lambda'}$$