

1. 卡尔曼滤波算法

对于线性数据同化问题

$$\text{演化方程: } x_{n+1} = Fx_n + \omega_{n+1}, \quad \omega_{n+1} \sim \mathcal{N}(0, \Sigma_\omega) \quad (1)$$

$$\text{观测方程: } y_{n+1} = Gx_{n+1} + \eta_{n+1}, \quad \eta_{n+1} \sim \mathcal{N}(0, \Sigma_\eta) \quad (2)$$

定义 $Y_n = \{y_\ell\}_{\ell=1}^n$, 卡尔曼滤波算法分为预测步骤和分析步骤近似, 分别近似预测分布 $\hat{\rho}_n(x_n) = \rho(x_n|Y_{n-1})$ 和滤波分布 $\rho_n(x_n) := \rho(x_n|Y_n)$ 。

它们满足如下迭代关系

$$\begin{aligned} \hat{\rho}_{n+1}(x_{n+1}) &= \mathcal{N}(x; \hat{m}_{n+1}, \hat{C}_{n+1}) & \hat{m}_{n+1} &= Fm_n & \hat{C}_{n+1} &= FC_nF^T + \Sigma_\omega \\ \rho_{n+1}(x_{n+1}) &= \mathcal{N}(x; m_{n+1}, C_{n+1}) & m_{n+1} &= \hat{m}_{n+1} + K_{n+1}d_{n+1} & C_{n+1} &= (I - K_{n+1}H)\hat{C}_{n+1} \end{aligned}$$

其中

$$d_{n+1} = y_{n+1} - H\hat{m}_{n+1} \quad S_{n+1} = H\hat{C}_{n+1}H^T + \Sigma_\eta \quad K_{n+1} = \hat{C}_{n+1}H^T S_{n+1}^{-1}$$

对于演化步骤

$$\begin{aligned} \hat{\rho}_{n+1}(x_{n+1}) &= \rho(x_{n+1}|Y_n) = \int \rho(x_{n+1}|x_n, Y_n)\rho(x_n|Y_n)dx_n = \int \rho(x_{n+1}|x_n)\rho(x_n|Y_n)dx_n \\ &= \int \mathcal{N}(x_{n+1}; Fx_n, \Sigma_\omega)\mathcal{N}(x_n; m_n, C_n)dx_n \\ &\propto \int \exp\left(-\frac{1}{2}(x_{n+1} - Fx_n)^T \Sigma_\omega^{-1}(x_{n+1} - Fx_n) - \frac{1}{2}(x_n - m_n)^T C_n^{-1}(x_n - m_n)\right)dx_n \\ &\propto \int \exp\left(-\frac{1}{2}x_n^T (F^T \Sigma_\omega^{-1} F + C_n^{-1})x_n - \frac{1}{2}x_n^T - m_n)^T C_n^{-1}(x_n - m_n)\right)dx_n \end{aligned}$$

证明

我们采用归纳法证明, 根据先验, 我们有 $\rho_0(x_0) = \mathcal{N}(x; m_0, C_0)$

对于演化步骤

$$\begin{aligned} \hat{\rho}_{n+1}(x_{n+1}) &= \rho(x_{n+1}|Y_n) = \int \rho(x_{n+1}|x_n, Y_n)\rho(x_n|Y_n)dx_n = \int \rho(x_{n+1}|x_n)\rho(x_n|Y_n)dx_n \\ &= \int \mathcal{N}(x_{n+1}; Fx_n, \Sigma_\omega)\mathcal{N}(x_n; m_n, C_n)dx_n \\ &\propto \int \exp\left(-\frac{1}{2}(x_{n+1} - Fx_n)^T \Sigma_\omega^{-1}(x_{n+1} - Fx_n) - \frac{1}{2}(x_n - m_n)^T C_n^{-1}(x_n - m_n)\right)dx_n \\ &\propto \int \exp\left(-\frac{1}{2}x_n^T (F^T \Sigma_\omega^{-1} F + C_n^{-1})x_n + x_n^T (C_n^{-1}m_n + F^T \Sigma_\omega^{-1}x_{n+1}) - \frac{1}{2}x_{n+1}^T \Sigma_\omega^{-1}x_{n+1}\right)dx_n \\ &\propto \int \exp\left(-\frac{1}{2}(x_n - r_n)^T (F^T \Sigma_\omega^{-1} F + C_n^{-1})(x_n - r_n) + \frac{1}{2}r_n^T (F^T \Sigma_\omega^{-1} F + C_n^{-1})r_n - \frac{1}{2}x_{n+1}^T \Sigma_\omega^{-1}x_{n+1}\right)dx_n \\ \text{使用 } r_n &= (F^T \Sigma_\omega^{-1} F + C_n^{-1})^{-1}(C_n^{-1}m_n + F^T \Sigma_\omega^{-1}x_{n+1}) \\ &\propto \exp\frac{1}{2}\left((C_n^{-1}m_n + F^T \Sigma_\omega^{-1}x_{n+1})^T (F^T \Sigma_\omega^{-1} F + C_n^{-1})^{-1}(C_n^{-1}m_n + F^T \Sigma_\omega^{-1}x_{n+1}) - \frac{1}{2}x_{n+1}^T \Sigma_\omega^{-1}x_{n+1}\right) \\ &\propto \exp\left(-\frac{1}{2}x_{n+1}^T (\Sigma_\omega^{-1} - \Sigma_\omega^{-1}F(F^T \Sigma_\omega^{-1}F + C_n^{-1})^{-1}F\Sigma_\omega^{-1})x_{n+1} + x_{n+1}^T \Sigma_\omega^{-1}F(F^T \Sigma_\omega^{-1}F + C_n^{-1})^{-1}C_n^{-1}m_n\right) \\ &\propto \exp\left(-\frac{1}{2}(x_{n+1} - Fm_n)^T (F^T C_n F + \Sigma_\omega)^{-1}(x_{n+1} - Fm_n)\right) \\ &\propto \mathcal{N}(x_{n+1}; Fm_n, F^T C_n F + \Sigma_\omega) \end{aligned}$$

另一种思考方式

$$\begin{aligned} \hat{\rho}_{n+1}(x_{n+1}) &= \rho(x_{n+1}|Y_n) \sim \rho(Fx_n + \omega_{n+1}|Y_n) \\ \mathbb{E}[Fx_n + \omega_{n+1}|Y_n] &= F\mathbb{E}[x_n|Y_n] + \mathbb{E}[\omega_{n+1}|Y_n] = Fm_n \\ \text{Cov}[Fx_n + \omega_{n+1}|Y_n] &= \mathbb{E}[(Fx_n + \omega_{n+1} - Fm_n)(Fx_n + \omega_{n+1} - Fm_n)^T|Y_n] \\ &= \mathbb{E}[(Fx_n - Fm_n)(Fx_n - Fm_n)^T|Y_n] + \mathbb{E}[\omega_{n+1}\omega_{n+1}^T|Y_n] \\ &= FC_nF^T + \Sigma_\omega \end{aligned}$$

对于分析步骤, 我们使用贝叶斯法则

$$\begin{aligned} \rho_{n+1}(x_{n+1}) &= \rho(x_{n+1}|Y_{n+1}) = \rho(x_{n+1}|Y_n, y_{n+1}) = \frac{\rho(y_{n+1}|x_{n+1}, Y_n)\rho(x_{n+1}|Y_n)}{\rho(y_{n+1}|Y_n)} \\ &\propto \rho(y_{n+1}|x_{n+1}, Y_n)\rho(x_{n+1}|Y_n) \propto \rho(y_{n+1}|x_{n+1})\rho(x_{n+1}|Y_n) \\ &\propto \mathcal{N}(y_{n+1}; Hx_{n+1}, \Sigma_\eta)\mathcal{N}(x_{n+1}; \hat{m}_{n+1}, \hat{C}_{n+1}) \\ &\propto \exp\left(-\frac{1}{2}(y_{n+1} - Hx_{n+1})^T \Sigma_\eta^{-1}(y_{n+1} - Hx_{n+1}) - \frac{1}{2}(x_{n+1} - \hat{m}_{n+1})^T \hat{C}_{n+1}^{-1}(x_{n+1} - \hat{m}_{n+1})\right) \\ &\propto \mathcal{N}(x_{n+1}; m_{n+1}, C_{n+1}) \end{aligned}$$

其中

$$C_{n+1} = (H^T \Sigma_\eta^{-1} H + \hat{C}_{n+1}^{-1})^{-1} \quad m_{n+1} = (H^T \Sigma_\eta^{-1} H + \hat{C}_{n+1}^{-1})^{-1}(H^T \Sigma_\eta^{-1} y_{n+1} + \hat{C}_{n+1}^{-1} \hat{m}_{n+1})$$

我们可以进一步简化

$$\begin{aligned} m_{n+1} &= \hat{m}_{n+1} + \hat{C}_{n+1}H^T(\Sigma_\eta + H\hat{C}_{n+1}H^T)^{-1}(y_{n+1} - H\hat{m}_{n+1}) \\ C_{n+1} &= \hat{C}_{n+1} - \hat{C}_{n+1}H^T(\Sigma_\eta + H\hat{C}_{n+1}H^T)^{-1}H\hat{C}_{n+1} \end{aligned}$$

因此我们可以定义

$$d_{n+1} = y_{n+1} - H\hat{m}_{n+1} \quad S_{n+1} = H\hat{C}_{n+1}H^T + \Sigma_\eta \quad K_{n+1} = \hat{C}_{n+1}H^T S_{n+1}^{-1}$$

2. 卡尔曼滤波的最优性

对于任意序列 $\{z_n\}$, 我们有

$$\mathbb{E}[|x_n - m_n|^2|Y_n] \leq \mathbb{E}[|x_n - z_n|^2|Y_n]$$

证明

$$\begin{aligned} \mathbb{E}[|x_n - z_n|^2|Y_n] &= \mathbb{E}[|x_n - m_n + m_n - z_n|^2|Y_n] \\ &= \mathbb{E}[|x_n - m_n|^2 + |m_n - z_n|^2 + 2\langle x_n - m_n, m_n - z_n \rangle|Y_n] \\ &\geq \mathbb{E}[|x_n - m_n|^2 + |m_n - z_n|^2|Y_n] \\ &\geq \mathbb{E}[|x_n - m_n|^2|Y_n] \end{aligned}$$

3. 卡尔曼平滑算法

对于贝叶斯平滑问题, 我们有

$$\rho_{\text{post}}(X; Y) = \frac{1}{Z} e^{-\Phi(X, Y)} \rho_{\text{prior}}(X) \propto e^{-\Phi_R(X, Y)}$$

其中

$$\begin{aligned} \Phi_R &= \frac{1}{2} \sum_{n=0}^{N-1} \|\Sigma_\eta^{-1/2}(y_{n+1} - Hx_{n+1})\|^2 + \frac{1}{2} \sum_{n=0}^{N-1} \|\Sigma_\omega^{-1/2}(x_{n+1} - Fx_n)\|^2 + \frac{1}{2} \|C_0^{-1/2}(x_0 - m_0)\|^2 \\ &= \frac{1}{2} (x - m_{\text{post}})^T C_{\text{post}}^{-1} (x - m_{\text{post}}) \end{aligned}$$

我们有

$$\nabla_x \Phi_R = C_{\text{post}}^{-1} (x - m_{\text{post}})$$

由于

$$\begin{aligned} \nabla_{x_0} \Phi_R &= -F^T \Sigma_\omega^{-1} (x_1 - Fx_0) + C_0^{-1} (x_0 - m_0) \\ \nabla_{x_n} \Phi_R &= -H^T \Sigma_\eta^{-1} (y_n - Hx_n) - F^T \Sigma_\omega^{-1} (x_{n+1} - Fx_n) + \Sigma_\omega^{-1} (x_n - Fx_{n-1}) \quad 0 < n < N \\ \nabla_{x_N} \Phi_R &= -H^T \Sigma_\eta^{-1} (y_N - Hx_N) + \Sigma_\omega^{-1} (x_N - Fx_{N-1}) \end{aligned}$$

定义 $r = C_{\text{post}}^{-1} m_{\text{post}}$, r 满足

$$\begin{aligned} r_0 &= C_0^{-1} m_0 \\ r_n &= -H^T \Sigma_\eta^{-1} y_n \quad 0 < n \leq N \end{aligned}$$

我们得到 $\Omega = C_{\text{post}}^{-1}$ 是分块三对角矩阵

$$\begin{aligned} \nabla_{x_0} \nabla_{x_0} \Phi_R &= F^T \Sigma_\omega^{-1} F + C_0^{-1} & \nabla_{x_0} \nabla_{x_1} \Phi_R &= -F^T \Sigma_\omega^{-1} \\ \nabla_{x_n} \nabla_{x_{n+1}} \Phi_R &= -F^T \Sigma_\omega^{-1} & \nabla_{x_n} \nabla_{x_n} \Phi_R &= H^T \Sigma_\eta^{-1} H + F^T \Sigma_\omega^{-1} F + \Sigma_\omega^{-1} \quad 0 < n < N \\ \nabla_{x_N} \nabla_{x_N} \Phi_R &= H^T \Sigma_\eta^{-1} H + \Sigma_\omega^{-1} \end{aligned}$$

并且 Ω 正定, 否则存在 $x \neq 0$ 使得 $x^T \Omega x = 0$, 即

$$0 = \frac{1}{2} \sum_{n=0}^{N-1} \|\Sigma_\eta^{-1/2} Hx_{n+1}\|^2 + \frac{1}{2} \sum_{n=0}^{N-1} \|\Sigma_\omega^{-1/2} (x_{n+1} - Fx_n)\|^2 + \frac{1}{2} \|C_0^{-1/2} x_0\|^2$$

因此 $x_0 = 0$ 并且 $x_{n+1} = Fx_n = 0$, 导出矛盾。

4. 证明

因为 Ω 正定, Ω_n 正定。

$$m_N^{\text{smoothing}} = \int \rho(X_N|Y_N) x_N dx_1 dx_2 \cdots dx_N = \int \rho(x_N|Y_N) x_N dx_N = m_N^{\text{filtering}}$$