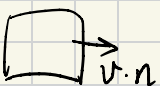


# 科学机器学习简介

## 1. 可压缩 NS 方程

$\rho$ : 密度     $\vec{v}$ : 速度

### ① 质量守恒


$$m = \int \rho \cdot d\Omega$$

$$\Delta m = - \int \rho (\vec{v} \cdot \vec{n}) \cdot \Delta t \, dS$$

$$\frac{\Delta m}{\Delta t} = \frac{d}{dt} \int \rho \, d\Omega = - \int \rho \vec{v} \cdot \vec{n} \, dS$$

$$= - \int \text{div}(\rho \vec{v}) \, dS$$

$$\frac{d\rho}{dt} + \nabla(\rho \vec{v}) = 0$$

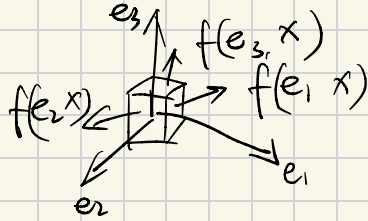
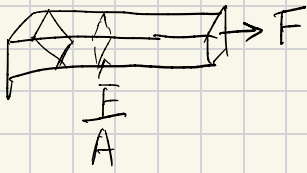
### ② 动量守恒

$$\Delta \int \rho \vec{v} \cdot d\Omega = - \int (\rho \vec{v}) (\vec{v} \cdot \vec{n}) \Delta t \, dS$$

$$+ \int f(\vec{n}, x) \, dS \cdot \Delta t$$

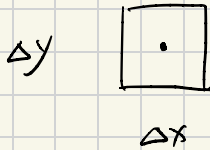
(pascal)   
  $\rightarrow$  表面作用力

$f(\vec{n}, x)$ : 应力, 物体由于外因而变形时, 在物体内各部分之间产生相互作用的内力, 单位面积上的内力称为应力。



$$f(\mathbf{n}, \vec{x}) = \bar{\sigma} \cdot \vec{n} \quad \bar{\sigma} = \text{应力张量} (\mathbb{R}^{3 \times 3})$$

$\bar{\sigma}$ : 对称 (2D 情况), 考虑小方块



$$\bar{\sigma} = \begin{pmatrix} \sigma_{xx} & \sigma_{xy} \\ \sigma_{yx} & \sigma_{yy} \end{pmatrix}$$

$$\text{角动量守恒: } \sum \mathbf{r}_i \times \mathbf{f}_i = I \dot{\omega} \quad I = \int \rho |\mathbf{r}|^2 dV \propto (\Delta x \Delta y)^2$$

$$\text{右边: } \frac{\Delta x}{2} \vec{e}_x \times (\bar{\sigma} \cdot \vec{e}_x + o(\Delta y)) \Delta y = \frac{\Delta x \Delta y}{2} \sigma_{xy}$$

$$\text{上边: } \frac{\Delta y}{2} \vec{e}_y \times (\bar{\sigma} \cdot \vec{e}_y + o(\Delta x)) \Delta x = -\frac{\Delta x \Delta y}{2} \sigma_{yx}$$

$$\Delta x \Delta y (\sigma_{xy} - \sigma_{yx}) = I \dot{\omega}$$

$$\Rightarrow \sigma_{xy} - \sigma_{yx} \approx o(\Delta x \Delta y)$$

$$\Rightarrow \sigma_{xy} = \sigma_{yx}$$

流体:

$$\text{应力 } \vec{\sigma} \cdot \vec{n} = -p \vec{n} + \vec{\tau} \cdot \vec{n}$$

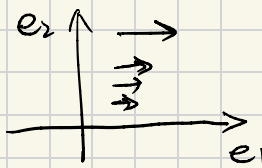
$$\vec{\tau} = \vec{\tau}(\nabla \vec{v})$$

$\tau$ : 对称 (角动量守恒)

牛顿流体 (假设)

$$\vec{\tau} = \mu (\nabla \vec{v} + \nabla \vec{v}^T) - \frac{2}{3} \mu (\nabla \cdot \vec{v}) \mathbf{I}$$

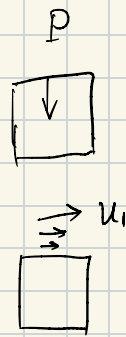
$$\begin{bmatrix} 2\mu \frac{\partial v_1}{\partial x_1} - \frac{2}{3} \mu \nabla \cdot \vec{v} & \mu \left( \frac{\partial v_1}{\partial x_2} + \frac{\partial v_2}{\partial x_1} \right) \\ \mu \left( \frac{\partial v_2}{\partial x_1} + \frac{\partial v_1}{\partial x_2} \right) & \dots \end{bmatrix}$$



$n = (0, 1, 0)$

$f = \sigma n = \left[ \mu \left( \frac{\partial v_1}{\partial x_2} + \frac{\partial v_2}{\partial x_1} \right) \dots \right]$

$$\frac{d}{dt}(\rho \vec{v}) + \begin{pmatrix} \nabla \cdot \rho \vec{v} v_1 \\ \nabla \cdot \rho \vec{v} v_2 \\ \nabla \cdot \rho \vec{v} v_3 \end{pmatrix} = \nabla \cdot (-p \mathbf{I} + \vec{\tau})$$



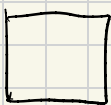
$$\vec{\tau} = \vec{\tau}(\nabla \vec{v})$$

### ③ 能量守恒

内能  $pe$

动能  $\frac{1}{2} \rho v \cdot \vec{v}$

$$E = pe + \frac{1}{2} \rho v \cdot \vec{v}$$



小块

质量交互

$$\Delta \int E d\Omega = - \int E (\vec{v} \cdot \vec{n}) \Delta t d\Omega$$

$$+ \int \underbrace{\vec{f} \cdot \vec{v}}_{\text{做功}} - \underbrace{\vec{q} \cdot \vec{n}}_{\text{热传导}} d\Omega$$

$$f = \sigma \cdot \vec{n}$$

傅立叶热传导定律:  $\vec{q} = -k \nabla T$

$$\frac{\partial E}{\partial t} + \nabla \cdot ((E+p)\vec{v}) = \nabla \cdot (\tau \cdot \vec{v} + k \nabla T)$$

推广：简化方程

$$\text{热方程: } e = c_v T$$

$$\frac{\partial T}{\partial t} = \nabla(k \nabla T)$$

对流扩散方程

$$\frac{\partial q}{\partial t} + \nabla(q \vec{v}) = \nabla(k \nabla q)$$

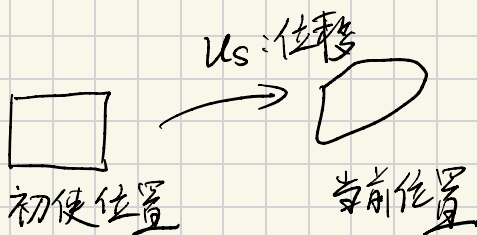
Burgers 方程

$$\frac{\partial u}{\partial t} + \frac{\partial}{\partial x} \left( \frac{1}{2} u^2 \right) = 0$$

# 固体方程

动量守恒方程

物质单元



$$\Delta \int \rho_s \dot{u}_s d\Omega = \int \underbrace{\tau \cdot \vec{n}}_{\text{表面应力}} d\partial\Omega \Delta t + \int \underbrace{f}_{\text{外力}} d\Omega \Delta t$$

$$\frac{d}{dt} \int \rho_s \dot{u}_s d\Omega = \int \nabla \tau d\Omega + \int f d\Omega$$

$$\frac{d}{dt} \int \rho_s d\Omega = 0 \quad (\text{质量守恒})$$

$$\rho_s \ddot{u}_s = \nabla \tau + f \quad (\text{当前位置})$$

应力张量  $\tau$

$$\text{应变张量 } \epsilon = \frac{1}{2} (\nabla u_s + \nabla u_s^T)$$

本构关系

$$\tau = \tau(\epsilon)$$

推广：简化方程

波动方程

$$\ddot{u} = \Delta u$$