

Robust Inversion, Dimensionality Reduction, and Randomized Sampling

—Course Presentation

Shan You, Kai Zheng, Cong Fang

December 15, 2014

Outline

- 1 Why dimension reduction
- 2 Random Sampling
 - Data Averaging
 - Sampling with and without replacement

$$\text{Recall : } \min \phi(x) = \frac{1}{m} \sum_{i=1}^m \phi_i(x),$$

$$\text{where } \phi_i(x) = \rho(r_i(x)) = \rho(d_i - F_i(x)q_i)$$

Disadvantage: Expensive Computation

How to solve? Stochastic Gradient Descent

$$\text{Recall : } \min \phi(x) = \frac{1}{m} \sum_{i=1}^m \phi_i(x),$$

$$\text{where } \phi_i(x) = \rho(r_i(x)) = \rho(d_i - F_i(x)q_i)$$

Disadvantage: Expensive Computation

How to solve? Stochastic Gradient Descent

$$\text{Recall : } \min \phi(x) = \frac{1}{m} \sum_{i=1}^m \phi_i(x),$$

$$\text{where } \phi_i(x) = \rho(r_i(x)) = \rho(d_i - F_i(x)q_i)$$

Disadvantage: Expensive Computation

How to solve? Stochastic Gradient Descent

Outline

- 1 Why dimension reduction
- 2 Random Sampling
 - Data Averaging
 - Sampling with and without replacement

When loss function is square function,

$$\phi(x) = \frac{1}{m} \text{tr}(R(x)^T R(x))$$

where $R(x) = [r_1(x), r_2(x), \dots, r_m(x)]$

'New Data': $\tilde{d}_j = \sum_{i=1}^m w_{ij} d_i$, $\tilde{q}_j = \sum_{i=1}^m w_{ij} q_i$, $j = 1, \dots, s$
 $\tilde{r}_j(x) = \tilde{d}_j - F(x) \tilde{q}_j$, $R_W(x) := [\tilde{r}_1(x), \tilde{r}_2(x), \dots, \tilde{r}_s(x)]$

$$R_W(x) = R(x)W$$

$$\phi_W(x) = \frac{1}{s} \sum_{j=1}^s \|\tilde{r}_j(x)\|^2 = \frac{1}{s} \text{tr}(R_W(x)^T R_W(x))$$

Proposition

If $\mathbb{E}[WW^T] = I$, then

$$\mathbb{E}[\phi_W(\mathbf{x})] = \phi(\mathbf{x}), \quad \mathbb{E}[\nabla\phi_W(\mathbf{x})] = \nabla\phi(\mathbf{x})$$

Disadvantage: Conclusion holds only for 2-norm.

Proposition

If $\mathbb{E}[WW^T] = I$, then

$$\mathbb{E}[\phi_W(\mathbf{x})] = \phi(\mathbf{x}), \quad \mathbb{E}[\nabla\phi_W(\mathbf{x})] = \nabla\phi(\mathbf{x})$$

Disadvantage: Conclusion holds only for 2-norm.

Sample a small subset $\mathcal{S} \subset \{1, \dots, m\}$

$$\phi_{\mathcal{S}}(\mathbf{x}) = \frac{1}{s} \sum_{i \in \mathcal{S}} \phi_i(\mathbf{x}), \quad \nabla \phi_{\mathcal{S}}(\mathbf{x}) = \frac{1}{s} \sum_{i \in \mathcal{S}} \nabla \phi_i(\mathbf{x})$$

$$\mathbb{E}[\phi_{\mathcal{W}}(\mathbf{x})] = \phi(\mathbf{x}), \quad \mathbb{E}[\nabla \phi_{\mathcal{W}}(\mathbf{x})] = \nabla \phi(\mathbf{x})$$

In each iteration step, cost is about $\frac{s}{m}$ -fraction of the true cost.

Error Analysis

What we care about are the sample gradient.

$$e := \nabla\phi_S - \nabla\phi$$

$$\mathbb{E}[\|e\|^2] = \mathbb{V}[\|\nabla\phi_S\|]$$

$$\sigma_g := \frac{1}{m-1} \sum_{i=1}^m \|\nabla\phi_i - \nabla\phi\|^2$$

$$\mathbb{E}[\|e\|^2] = \frac{1}{s} \left(1 - \frac{s}{m}\right) \sigma_g \quad (\text{without replacement})$$

$$\mathbb{E}[\|e\|^2] = \frac{1}{s} \sigma_g \quad (\text{with replacement})$$